

## Subsurface Mapping GPR

# **GM8000**

#### Modular multichannel GPR mobile mapping system for the subsurface



#### Versatility

Interchangeable GPR arrays for near surface and deep detection to scale your solution easily and approach new applications.



### **Accuracy**

The highest density of information in all three dimensions, accurately mapped even in challenging conditions.



#### **Efficiency**

Easy to set up, operate, and get insights from.

Data collection at high speed and direct path into the office.













| Radar technology  | Stepped-frequency GPR   |
|---|---|
| Modulated frequency range   | 500 – 3000 MHz <sup>2</sup>   30 – 750 MHz <sup>3</sup>   |
| Number of channels  | 71 (VV) + 31 (HH) <sup>2</sup>   23 (VV) <sup>3</sup>   |
| Channel spacing   | 2.5 cm (VV), 5.5 cm (HH) <sup>2</sup>   7.5 cm <sup>3</sup>   |
| Scan width  | 1.75 m <sup>2</sup>   1.67 m <sup>3</sup>   |
| Scan rate   | 27500 scans/s <sup>2</sup>   22000 scans/s <sup>3</sup>   |
| Time window   | 35 ns <sup>2</sup>   100 ns <sup>3</sup>  |
| Acquisition speed   | Up to 80 Km/h $^{24}$   Up to 180 Km/h $^{35}$  |
| Spatial interval  | Up to 100 scans/m   |
| Dimensions  | 414 x 533 x 757 mm + 591 x 630 x 957 mm   |
| Weight  | 81 Kg <sup>2</sup>  |
| Odometry  | Doppler radar or wheel speed sensor   |
| Ingress protection (IP) / sealing   | IP65  |
|   |   |
| Towing system   | Rear hitch, 50 mm ball  |
| Towing system  Shock absorption system  | Rear hitch, 50 mm ball<br>Hydraulic   |
|   | ,   |
| Shock absorption system   | Hydraulic   |
| Shock absorption system  Power supply   | Hydraulic Power-over-Ethernet / External 12V  |
| Shock absorption system  Power supply  Operating temperature  | Hydraulic  Power-over-Ethernet / External 12V  -10° to 50°C   14° to 122° F   |
| Shock absorption system  Power supply  Operating temperature  Operating humidity  | Hydraulic  Power-over-Ethernet / External 12V  -10° to 50°C   14° to 122° F  <95% RH, non-condensing  USB-C, USB-A, 2x Ethernet + Power, 2x Lemo 6, 2x ODU Antenna connector, Universal I/O   |
| Shock absorption system  Power supply  Operating temperature  Operating humidity  Connectivity  | Hydraulic  Power-over-Ethernet / External 12V  -10° to 50°C   14° to 122° F  <95% RH, non-condensing  USB-C, USB-A, 2x Ethernet + Power, 2x Lemo °, 2x ODU Antenna connector, Universal I/O (UART, CAN-Bus)   |
| Shock absorption system  Power supply  Operating temperature  Operating humidity  Connectivity  GNSS satellites   | Hydraulic  Power-over-Ethernet / External 12V  -10° to 50°C   14° to 122° F  <95% RH, non-condensing  USB-C, USB-A, 2x Ethernet + Power, 2x Lemo 6, 2x ODU Antenna connector, Universal I/O (UART, CAN-Bus)  Multiband GPS + Glonass + Galileo + Beidou   |
| Shock absorption system  Power supply  Operating temperature  Operating humidity  Connectivity  GNSS satellites  GNSS real-time corrections                             | Hydraulic  Power-over-Ethernet / External 12V  -10° to 50°C   14° to 122° F  <95% RH, non-condensing  USB-C, USB-A, 2x Ethernet + Power, 2x Lemo 6, 2x ODU Antenna connector, Universal I/O (UART, CAN-Bus)  Multiband GPS + Glonass + Galileo + Beidou  SSR augmentation / NRTK-compatible 7                               |
| Shock absorption system  Power supply  Operating temperature  Operating humidity  Connectivity  GNSS satellites  GNSS real-time corrections  GNSS real-time 3D accuracy | Hydraulic  Power-over-Ethernet / External 12V  -10° to 50°C   14° to 122° F  <95% RH, non-condensing  USB-C, USB-A, 2x Ethernet + Power, 2x Lemo 6, 2x ODU Antenna connector, Universal I/O (UART, CAN-Bus)  Multiband GPS + Glonass + Galileo + Beidou  SSR augmentation / NRTK-compatible 7  Typ. 1 - 5 cm   0.5 - 2 in 8 |

- 1. Running an up-to-date iOS version; recommended models: MacBook Pro® 2022 model or superior
- 2. In combination with 2x GX1 array modules
- 3. In combination with 2x GX2 array modules
- 4. At 100mm spacing
- 5. At 50mm spacing
- 6. For terrestrial positioning systems, an intermediate serial adapter to DB9 might be needed to output Pseudo NMEA GGA positions
- $\textbf{7.} \ \mathsf{Needs} \ \mathsf{an} \ \mathsf{active} \ \mathsf{Internet} \ \mathsf{connection} \ \mathsf{on} \ \mathsf{the} \ \mathsf{iPad}; \mathsf{NTRIP} \ \mathsf{corrections} \ \mathsf{in} \ \mathsf{RTCM3} \ \mathsf{format}$
- 8. The achieved accuracy is subject to atmospheric conditions, satellite geometry, observation time, etc.

#### **Our Accessories**

| Image | PartNumber | Description |
|-------|------------|-------------|
| HEE   | GX1        |             |
| H-10  | GX2        |             |

| Standards & Guidelines      | Description |
|-----------------------------|-------------|
| AS 5488-2013 ( Australia)   |             |
| NF_S70-003 ( France)        |             |
| UNI/PdR 26.01:2017 ( Italy) |             |
| ASCE 38-02 (United States)  |             |
| CSA S250 ( Canada)          |             |
| HSG47 ( United Kingdom)     |             |
| PAS128 (United Kingdom)     |             |
| ASTM D6432-11               |             |
| NCHRP Synesis 255           |             |
| SHRP H-672                  |             |
| SHRP S-300                  |             |
| SHRP S-325                  |             |

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